

COMPUTER AIDED POWER SYSTEM PROTECTION

Full Marks: 70
Time: 3 hours

Answer SIX questions including Q No. 1 which is compulsory.
The figures in the right hand margin indicate marks. *Symbols carry usual meaning.*

- Q1. Answer all questions. [2×10]
- a) What is Anti-aliasing filter? Explain.
 - b) Write short note on the performance of Instrument transformers.
 - c) What is the effect of increasing number of samples in a given window on the precision of DFT?
 - d) State Fourier series in trigonometric form as a cosine wave with phase angle.
 - e) What is the need for random processes in protective relaying?
 - f) Explain the Out-of-Step Protection in generators.
 - g) Explain the generator Backup Protection.
 - h) Write short note on counter measures against EMI.
 - i) State different hardware issues connected to substation relaying.
 - j) What do you understand by adaptive relaying?
- Q2. a) Explain the benefits obtained from computer relaying in power system protection. [5]
b) Explain the principle of working of any one type of analog to digital converter with a neat block diagram. [5]
- Q3. a) Explain the objectives and functions of a protection system. [5]
b) Discuss the protection schemes applied to transmission lines. [5]
- Q4. a) Explain the protection of series compensated transmission lines. [5]
b) Discuss the Kalman filter usage in power system protection. [5]
- Q5. a) Explain the sources of error in transmission line protective relaying. [5]
b) Draw the Program Flow Chart for Symmetrical component distance relay. [5]
- Q6. a) Explain Fast algorithm used for digital protection of power transformers. [5]
b) Discuss the Anti-Motoring Protection of synchronous generator. [5]
- Q7. a) Explain the implementation of practical travelling waves based protection relay. [5]
b) Explain the principle of operation of travelling wave differential relay used in protection of UHV transmission lines. [5]
- Q8. Write short notes on any TWO. [5×2]
- a) Fault generated traveling waves
 - b) Digital bus bar protection
 - c) Phasor measurement in dynamic state estimation.
 - d) Measurement of frequency and phase of a signal.